EAST Search History

EAST Search History (Prior Art)

Ref#	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S37	17	"5710498"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:08
S38	2	"20060186845"	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:17
S3 9	1555	(318/432).COLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/21 15:51
S40	55	S39 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 ad]2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 15:54
S41	55	S39 and position\$4 and (correct\$4 compensat\$4) and (feetdback (clos\$4 ad]2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:20
S42	26	S39 and position\$4 and (correct\$4 compensat\$4) and (feetback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:21

S43	10	S39 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 ad(2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/21 17:22
S44	1555	(318/432).OOLS.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:11
S45	10	S44 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4) and (feedback (clos\$4) adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 16:11
S46	9	S44 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 add [loop)) and gain and (feedback eror deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) same (differen\$4 eror deviat \$4 subtract\$4))	US POPUB; USPAT; EPO; JPO; DEFWIENT	OR	ON	2009/10/22

S47	9	S44 and position\$4 and (correct\$4 compensat\$4) and (feedback (clos\$4 ad]2 loop)) and gain\$4 and (differenc\$4 error deviat\$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) same (differenc\$4 error deviat\$4 subtract\$4))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22
S48	4	(("5371361") or ("5790692")).PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:21
S49	2	("20080024085").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 16:32
S51	295	"318"/\$7.ccls. and position\$4 and (correct \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf)	US PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON I	2009/10/22
S 52	259	"318"/\$7.cols. and position\$4 and (correct \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) same (differenc\$4 error deviat \$4 subtract\$4))	US-PGPUB; USPAT; EPO; JPO; DERWIENT	OR	ON	2009/10/22 17:37

S53	80	"318"/\$7.ccls. and position\$4 and (correct \$4 compensat\$4) and (fleedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum\$4 summation) same (differenc\$4 error deviat \$4 subtract\$4)) and ((filter\$4 lpf hpf)) and (gdd\$4 sum\$5 armation) same (differenc\$4 error deviat \$4 subtract\$4)) and (\$4 subtract\$4 subtract\$4) are (differenc\$4 error deviat\$4 subtract\$4)	US POPUB; USPAT, EPO; JPO; DERWIENT	OR .	ON	2009/10/22
\$54		"318"/\$7.cols. and position\$4 and (corred \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (fliter\$4 lpf hpf) and (fadd\$4 sum \$4 summation) same (differen\$4 error deviat \$4 subtract\$4)) and ((fliter\$4 lpf hpf) same gain\$4 same (differenc \$4 error deviat\$4 subtract\$4)) and (troque same (speed velocity))	US PGPUB; USPAT; EPO; JPO; DERWENT	OR .	ON	2009/10/22

SS55	53	"318"/\$7.ccis. and position\$4 and (correct \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 pf hpf) and ((add\$4 sum\$4 summation) ame (differenc\$4 error deviat \$4 subtract\$4)) and ((filter\$4 pf hpf) same gain\$4 same (differenc\$4 error deviat\$4 subtract\$4)) and ((troque same (speed velocity)) same position\$4 positi	US POPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22
\$56	47	"318"/\$7.cols. and position\$4 and (corred \$4 compensat\$4) and (feedback (clos\$4 adj2 loop)) and gain\$4 and (differenc\$4 error deviat \$4 subtract\$4) and (position\$4 near9 (correct \$4 compensat\$4)) and (velocity speed) and torque and (axis axes) and (add\$4 sum\$4 summation) and (filter\$4 lpf hpf) and ((add\$4 sum \$4 summation) near9 (differenc\$4 error deviat \$4)) and (filter\$4 lpf hpf) same gain\$4 same (differenc\$4 error deviat \$4 subtract\$4)) and ((torque same (speed velocity)) same position \$4)	US PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2009/10/22 17:45
S57	2	("6054827").PN.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	OFF	2009/10/22 17:48

^{10/24/2009 5:24:29} PM

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